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Sensors and Actuators in Electric Vehicles 1

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OUTLINE

- **Sensors in EVs:** Battery monitoring, motor control, chassis/driver inputs, ADAS/environmental sensors
- **Actuators in EVs:** Propulsion (motor/inverter), steering, braking, battery safety, thermal management
- **Control Systems:** How EV controllers use sensor data to drive actuators (feedback loops, regenerative braking example)
- **Future Trends:** X-by-wire systems, in-wheel motors, advanced sensor tech, intelligent diagnostics



Introduction: Why Sensors and Actuators Matter

Electric vehicles rely on a network of **sensors** and **actuators** to operate efficiently and safely. Sensors are essentially the “eyes and ears” of the EV, constantly monitoring variables like speed, temperature, and voltage, providing real-time data about the vehicle and its environment ([Introduction to Automotive Sensors and Actuators](#)).



Actuators are the “doers” – they take commands from the EV’s control units and translate electrical signals into physical action, from applying the brakes to steering the wheels or controlling motor torque ([Introduction to Automotive Sensors and Actuators](#)). This tight integration of sensing and actuation enables EVs to achieve high performance, energy efficiency, and safety far beyond what purely mechanical systems could do.



How EVs Use Sensors and Actuators

In an EV, sensors and actuators work together in closed-loop control. Sensors feed information to electronic control units (ECUs) about the vehicle's state – for example, wheel speed, pedal position, battery status, and motor RPM. The EV's control software (its “brain”) analyzes these inputs continuously and sends out commands to actuators to adjust the vehicle's operation in real time ([Adaptive Control Mechanisms for Electric Vehicles: A Study Based on Driving Environments](#)). For instance, if a sensor detects wheel slip, the control unit can signal an actuator (the motor controller or brake actuator) to reduce torque and restore traction. In essence, sensors provide the data and actuators carry out the actions, allowing the EV to dynamically respond to driver commands and driving conditions.....

Major Types of Sensors in EVs

(A comprehensive look at EV sensors alongside Prostech's solutions. - PROSTECH)

- **Position and Speed Sensors:** Detect positions, angles or rotational speeds of components. For example, motor shaft position sensors or wheel speed sensors provide critical feedback for control systems
- **Current Sensors:** Measure electrical current flow in various circuits (battery, inverter, charger). They help track energy usage and prevent overcurrent; in the BMS, current sensors report charging/discharging rates and battery state-of-health
- **Voltage Sensors:** Monitor the voltage levels of battery cells, modules, and the high-voltage bus. These sensors ensure each cell operates within safe limits and can detect faults like insulation failures or imbalances
- **Temperature Sensors:** Found throughout the EV (battery cells, motor windings, power electronics) to monitor thermal conditions. They enable thermal management systems to keep components in a safe operating range and can trigger protective actions if overheating is detected

Battery Monitoring Sensors: Voltage & Current

- **Cell/Pack Voltage Sensors:** Voltage sensors are attached to individual cells or modules to measure their voltage. The BMS uses this data to balance cells, prevent over-charge or over-discharge, and estimate the state-of-charge. In a typical EV, the BMS monitors the voltage of every cell string to ensure they remain within safe limits
- **Current Sensor (Shunt or Hall-effect):** A high-precision current sensor (often a Hall-effect device or shunt resistor) measures the battery pack's charge and discharge current. This sensor data is used to track how much power is going in or out of the battery, which helps compute the state-of-charge and state-of-health of the pack. It also enables detection of abnormal currents (short circuits or excessive discharge rates) so that the system can quickly disconnect the pack if needed.

Battery Monitoring Sensors: Temperature & Safety

- **Temperature Sensors: Thermistors or temperature probes** are placed on cells and coolant channels to constantly measure battery temperatures. Thermal management is crucial for lithium-ion batteries – they perform best in the ~15–45 °C range and can be damaged by extreme. The BMS relies on these temperature sensors to actively manage cooling/heating systems and to avoid conditions that could lead to thermal runaway.
- **Gas and Leak Detectors:** Advanced EV packs often include safety sensors such as **gas sensors** to detect any venting of flammable gases from cells, and **liquid leak sensors** to detect coolant intrusion. These are early warning devices – if a cell goes into thermal runaway and releases gas, a sensor can alert the BMS to trigger an alarm or take action. Likewise, a coolant leak detector can catch a coolant breach in the pack (which could cause short-circuits) so the system can be shut down.

Motor and Inverter Sensors

- **Rotor Position Sensors:** Most EV motors are AC synchronous machines that require rotor position feedback for control. A dedicated sensor such as a resolver or magnetic encoder tracks the exact angle of the motor's rotor. The inverter uses this feedback to apply current to the motor's windings with precise timing (field-oriented control). The result is efficient torque production across all speeds. For instance, Continental's e-motor rotor position sensor "accurately measures the angular position of the rotor shaft in synchronous motors to ensure efficient operation"
- **Current Sensors (Phase/Bus Current):** The inverter or motor controller is equipped with current sensors to measure the electric current flowing into the motor (either on each phase or the DC supply line). These sensors are crucial for torque control – they allow the controller to regulate motor current (and thus torque) within desired limits. They also serve a protection role: if a sudden spike or imbalance in current is detected, the system can react (for example, by shutting down the inverter). In EV applications, **open-loop Hall-effect sensors** and other designs are used to get fast readings of motor current. Open-loop current sensors respond in microseconds and are ideal for motor control, where ultra-high precision is less critical than quick detection



- **Motor/Inverter Temperature Sensors:** High-power motors and power electronics generate heat, so temperature sensors are embedded in these components as well. For example, motors typically have thermistors in the stator windings or near bearings to monitor internal temperatures. Similarly, the inverter's semiconductor modules have temperature sensors. The system uses these to prevent overheating – the controller can reduce power if a motor is running hot, or turn on cooling fans. Temperature feedback helps ensure reliability and prevent damage to the motor or inverter due to excessive heat

Chassis & Driver Input Sensors

- **Wheel Speed Sensors:** Each wheel in an EV has a speed sensor (usually a magnetic pickup on the wheel hub) that measures how fast the wheel is rotating. These are crucial for antilock braking (ABS), traction control, and electronic stability control (ESC) systems. In fact, the wheel speed sensor is often considered “the most important sensor” for vehicle dynamic control ([Springer](#)) – if a wheel is slipping or locking up, the control system will detect it via this sensor and command the brakes or motor to intervene.
- **Inertial Measurement Unit (IMU):** An IMU typically consisting of accelerometers and gyroscopic sensors is mounted in the vehicle to sense its motion (longitudinal/lateral acceleration and yaw/roll rates). These sensors tell the stability control system how the vehicle is moving in 3D space. , the ESC computer will see a discrepancy between the yaw rate and wheel speeds, and can activate actuators (brakes or motor torque adjustments) to help correct the trajectory. IMU data is also used for airbag deployment decisions (detecting a collision shock) and for advanced driver assistance. ESC computer will see a discrepancy between the yaw rate and wheel speeds, and can activate actuators (brakes or motor torque adjustments) to help correct the trajectory.



- **Pedal Position Sensors:** EVs use electronic “drive-by-wire” inputs for the accelerator and often the brake. The accelerator pedal has a position sensor (typically dual potentiometer or Hall-effect sensors) that measures how far the pedal is pressed. This sensor is essential – it tells the motor controller how much torque the driver is requesting. A smooth and precise response is critical for drivability. Likewise, brake pedal sensors (pressure sensors or travel sensors in brake-by-wire systems) detect how hard the driver is braking. In many EVs, this is used to blend regenerative braking with friction braking seamlessly. Although these pedal sensors are simple in principle, they are safety-critical and usually have redundant sensing elements.