

# MODELLING AND SIMULATION OF ELECTRIC VEHICLES

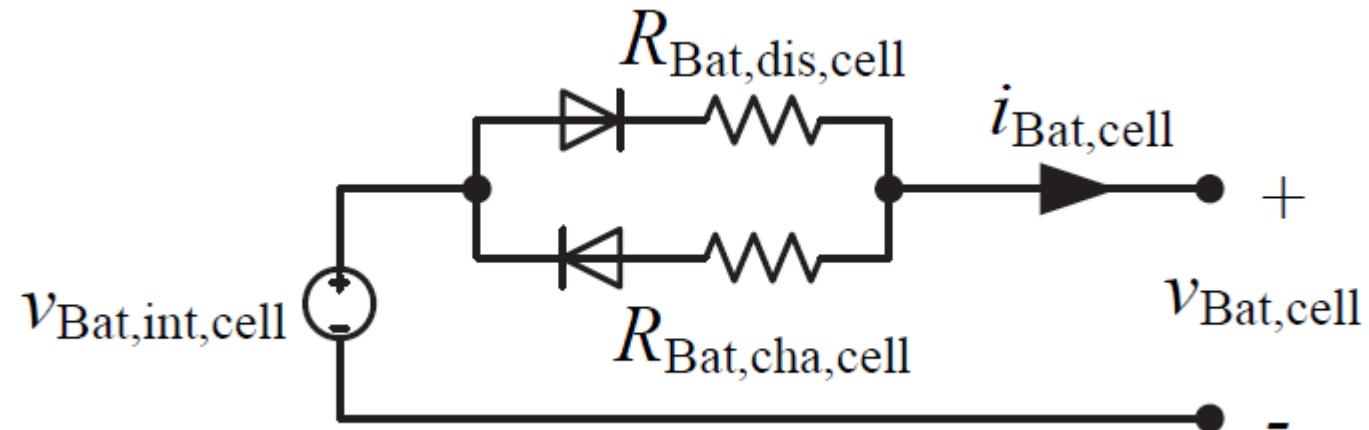
## Part 2

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# Vehicle modeling - battery electric model

- The battery electric model consists of an internal voltage source and two inner resistances used for charging and discharging. The two diodes are ideal and have only symbolics meaning, i.e., to be able to shift between the charging and discharging resistances. Discharging currents are treated as positive currents, i.e., charging currents are then negative.



Electric equivalent circuit diagram of a battery cell

# Vehicle modeling - battery electric model

$$v_{\text{Bat,cell}} = \begin{cases} v_{\text{Bat,int,cell}} - R_{\text{Bat,cell,dis}} i_{\text{Bat,cell}} & , i_{\text{Bat,cell}} \geq 0 \\ v_{\text{Bat,int,cell}} - R_{\text{Bat,cell,cha}} i_{\text{Bat,cell}} & , i_{\text{Bat,cell}} < 0, \end{cases} \quad (23)$$

where  $v_{\text{Bat,cell}}$  [V] Battery cell voltage  
 $v_{\text{Bat,int,cell}}$  [V] Internal battery cell voltage  
 $i_{\text{Bat,cell}}$  [A] Battery cell current  
 $R_{\text{Bat,cell,dis}}$  [ $\Omega$ ] Inner battery cell resistance during discharge mode  
 $R_{\text{Bat,cell,cha}}$  [ $\Omega$ ] Inner battery cell resistance during charge mode

$$R_{\text{Bat,cell,dis}} = a_{10} D_o D_{\text{Bat}}^{10} + a_9 D_o D_{\text{Bat}}^9 + a_8 D_o D_{\text{Bat}}^8 + a_7 D_o D_{\text{Bat}}^7 + a_6 D_o D_{\text{Bat}}^6 \\ + a_5 D_o D_{\text{Bat}}^5 + a_4 D_o D_{\text{Bat}}^4 + a_3 D_o D_{\text{Bat}}^3 + a_2 D_o D_{\text{Bat}}^2 + a_1 D_o D_{\text{Bat}} + a_0 \quad (24)$$

# Vehicle modeling - battery electric model

$$\begin{aligned} v_{\text{Bat,int,cell}} = & b_{10}D_oD_{\text{Bat}}^{10} + b_9D_oD_{\text{Bat}}^9 + b_8D_oD_{\text{Bat}}^8 + b_7D_oD_{\text{Bat}}^7 + b_6D_oD_{\text{Bat}}^6 \\ & + b_5D_oD_{\text{Bat}}^5 + b_4D_oD_{\text{Bat}}^4 + b_3D_oD_{\text{Bat}}^3 + b_2D_oD_{\text{Bat}}^2 + b_1D_oD_{\text{Bat}} + b_0 \end{aligned} \quad (25)$$

$$\begin{aligned} R_{\text{Bat,cell,cha}} = & c_{10}D_oD_{\text{Bat}}^{10} + c_9D_oD_{\text{Bat}}^9 + c_8D_oD_{\text{Bat}}^8 + c_7D_oD_{\text{Bat}}^7 + c_6D_oD_{\text{Bat}}^6 \\ & + c_5D_oD_{\text{Bat}}^5 + c_4D_oD_{\text{Bat}}^4 + c_3D_oD_{\text{Bat}}^3 + c_2D_oD_{\text{Bat}}^2 + c_1D_oD_{\text{Bat}} + c_0 \end{aligned} \quad (26)$$

where  $a_{10} = -634.0$ ,  $a_9 = 2942.1$ ,  $a_8 = -5790.6$ ,  $a_7 = 6297.4$ ,  $a_6 = -4132.1$ ,  $a_5 = 1677.7$   
 $a_4 = -416.4$ ,  $a_3 = 60.5$ ,  $a_2 = -4.8$ ,  $a_1 = 0.2$ ,  $a_0 = 0.0$   
 $b_{10} = -8848$ ,  $b_9 = 40727$ ,  $b_8 = -79586$ ,  $b_7 = 86018$ ,  $b_6 = -56135$ ,  $b_5 = -5565$   
 $b_4 = 784$ ,  $b_3 = -25$ ,  $b_2 = 55$ ,  $b_1 = 0$ ,  $b_0 = 4$   
 $c_{10} = 2056$ ,  $c_9 = -9176$ ,  $c_8 = 17147$ ,  $c_7 = -17330$ ,  $c_6 = 10168$ ,  $c_5 = -3415$   
 $c_4 = 578$ ,  $c_3 = 25$ ,  $c_2 = 3$ ,  $c_1 = 0$ ,  $c_0 = 0$

# Vehicle modeling - battery capacity model

- The inner voltage source, charging resistance, and discharge resistance all depend on the depth-of-discharge. The state-of-charge and depth-of-discharge depend on the integral of the current drawn or delivered to the battery, i.e.,

$$DoD_{Bat} = DoD_{Bat,ini} + \int \frac{i_{Bat,eq,cell}}{Q_{Bat,1,cell}} dt \quad (27)$$

$$SoC_{Bat} = 1 - DoD_{Bat} \quad (28)$$

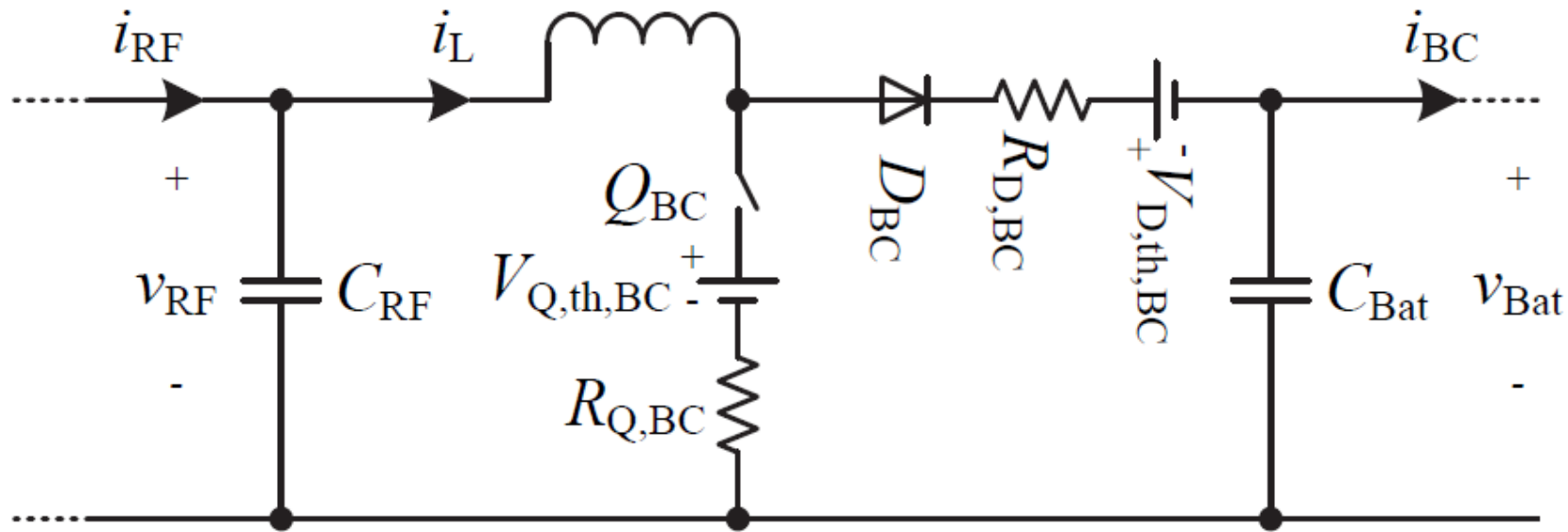
where  $DoD_{Bat}$  [—] Depth-of-discharge  
 $DoD_{Bat,ini}$  [—] Initial depth-of-discharge  
 $SoC_{Bat}$  [—] Battery state-of-charge  
 $i_{Bat,eq,cell}$  [A] Equivalent battery cell current

$$i_{Bat,eq,cell} = \begin{cases} I_{Bat,1,cell} \left( \frac{i_{Bat,cell}}{I_{Bat,1,cell}} \right)^k, & i_{Bat,cell} \geq 0 \\ \eta_{Bat,cha} i_{Bat,cell}, & i_{Bat,cell} < 0 \end{cases} \quad (29)$$

$$k = \begin{cases} 1, & i_{Bat,cell} \leq I_{Bat,1,cell} \\ 1.125, & i_{Bat,cell} > I_{Bat,1,cell} \end{cases} \quad (30)$$

where  $k$  [—] Peukert number  
 $\eta_{Bat,cha} = 0.95$  [—] Charging efficiency

# Vehicle modeling - boost converter



Electric circuit diagram of the boost converter

# Vehicle modeling - boost converter

- The power equations of the boost converter are given by:

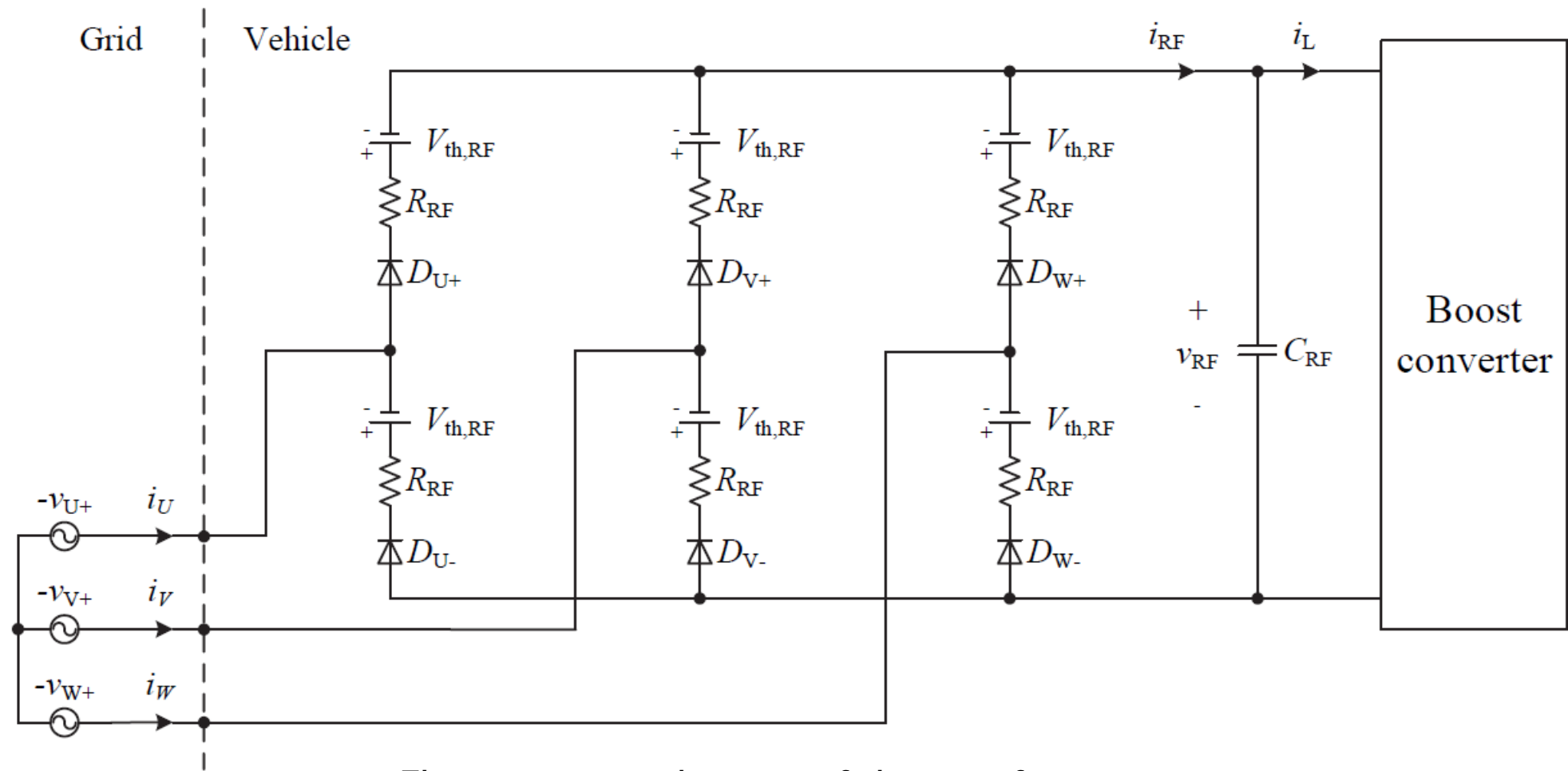
$$P_{\text{RF}} = V_{\text{RF}} i_{\text{RF}} = P_{\text{BC}} + P_{\text{Loss,BC}} \quad (31)$$

$$P_{\text{BC}} = V_{\text{Bat}} i_{\text{BC}} \quad (32)$$

$$P_{\text{Loss,BC}} = R_{\text{BC}} i_{\text{RF}}^2 + V_{\text{th,BC}} i_{\text{RF}}, \quad (33)$$

where $P_{\text{RF}}$	[W]	Input power of boost converter
$P_{\text{BC}}$	[W]	Output power of boost converter
$P_{\text{Loss,BC}}$	[W]	Power loss of boost converter
$V_{\text{RF}}$	[V]	Input voltage of boost converter
$V_{\text{th,BC}}$	[V]	Threshold voltage of switch and diode
$R_{\text{BC}}$	[ $\Omega$ ]	Resistance of switch and diode
$i_{\text{RF}}$	[A]	Input current of boost converter
$i_{\text{BC}}$	[A]	Output current of boost converter

# Vehicle modeling - rectifier



Electric circuit diagram of the rectifier



# Vehicle modeling - rectifier

$$i_{\text{RF}} = I_{\text{Grid}} \sqrt{\frac{3}{2}} \quad (34)$$

$$V_{\text{RF}} = \frac{3\sqrt{2}}{\pi} V_{\text{LL}} - 2R_{\text{RF}}i_{\text{RF}} - 2V_{\text{th,RF}} \quad (35)$$

$$P_{\text{RF}} = V_{\text{RF}}i_{\text{RF}} = P_{\text{Grid}} - P_{\text{RF,loss}} \quad (36)$$

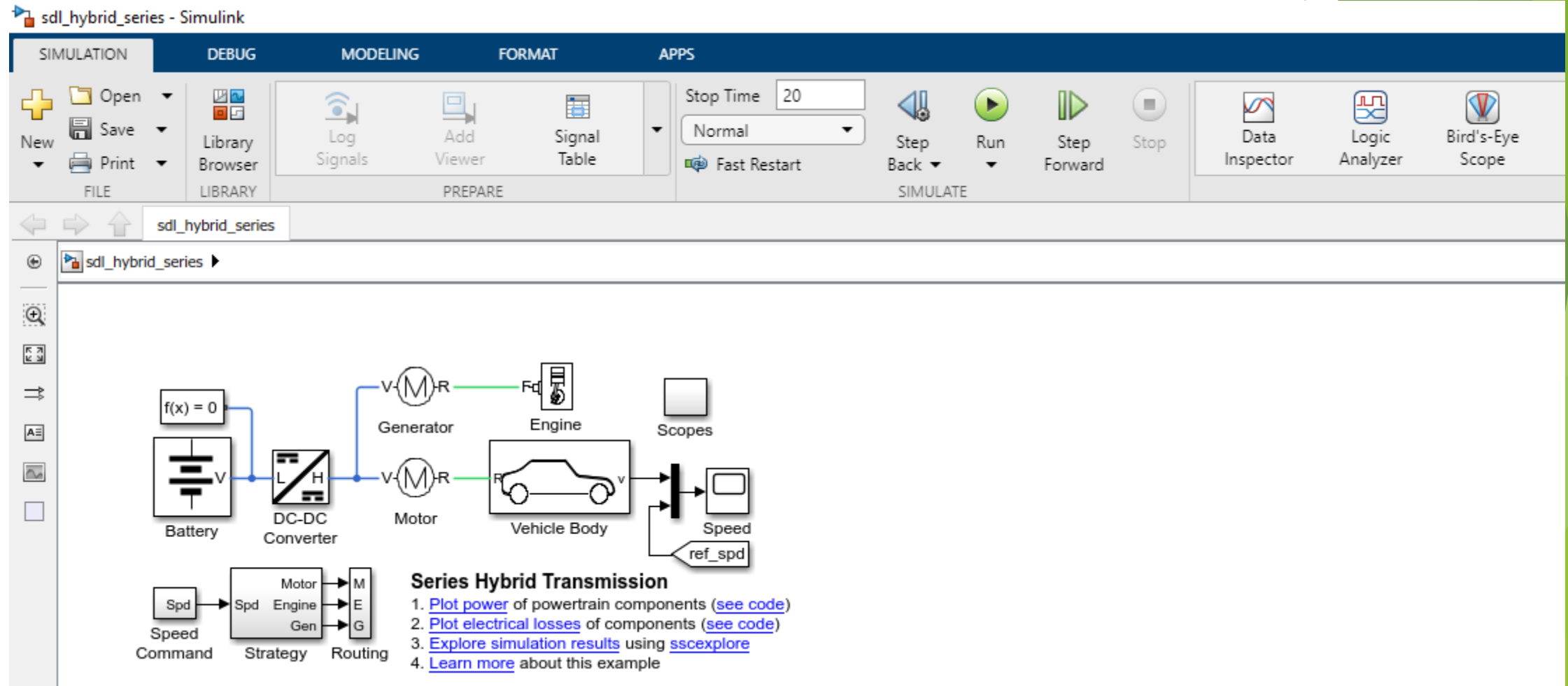
$$P_{\text{Grid}} = \frac{3\sqrt{2}}{\pi} V_{\text{LL}} I_{\text{RF}} \quad (37)$$

$$P_{\text{RF,loss}} = 2R_{\text{RF}}i_{\text{RF}}^2 + 2V_{\text{th,RF}}i_{\text{RF}}, \quad (38)$$

where

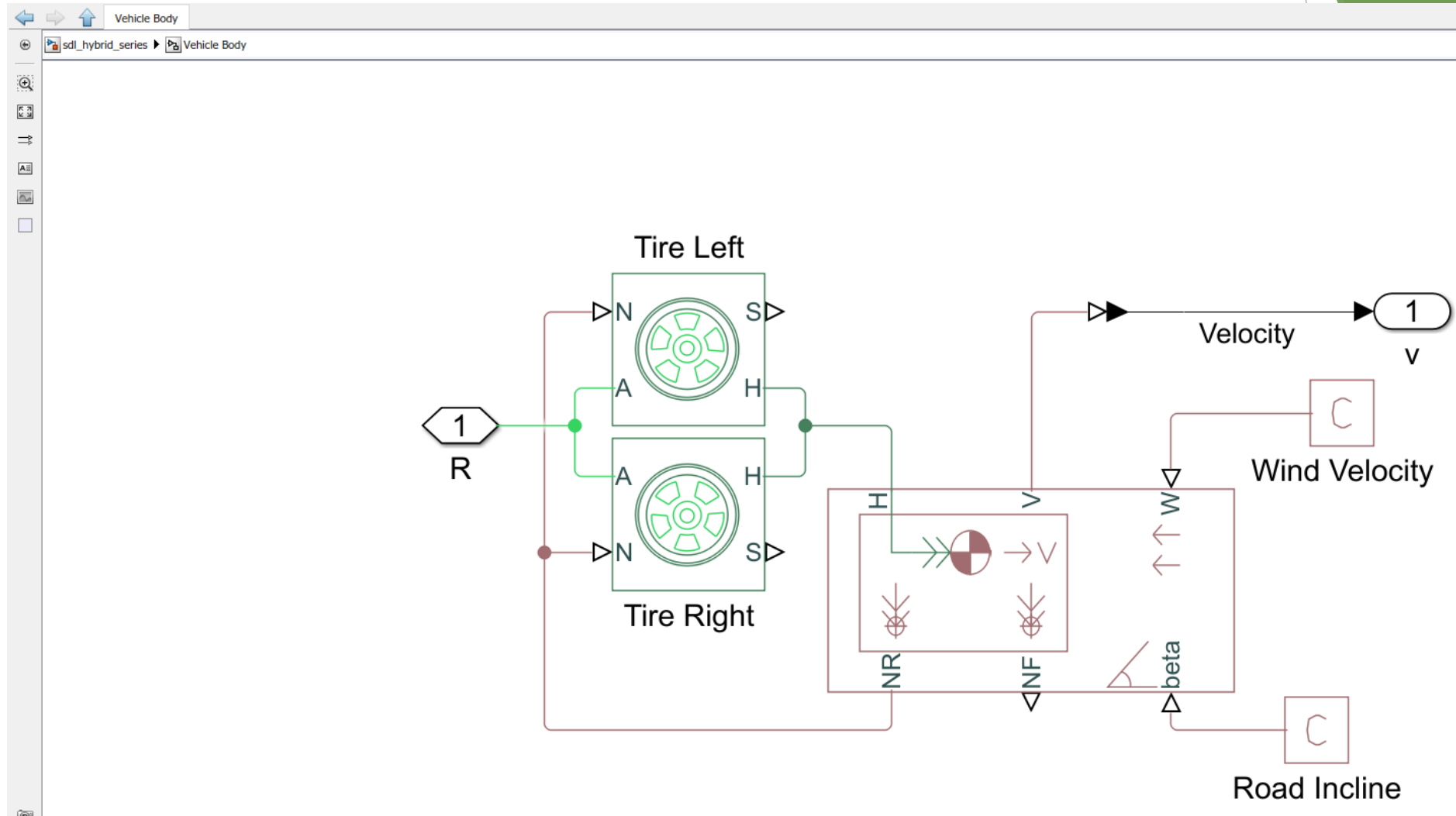
$I_{\text{Grid}}$	[A]	Grid RMS-current
$P_{\text{Grid}}$	[W]	Power of three phase grid
$P_{\text{loss,RF}}$	[W]	Total loss of the rectifier
$R_{\text{RF}}$	[Ω]	Resistance of switch and diode
$V_{\text{th,RF}}$	[V]	Threshold voltage of switch and diode

# Simulation of electric vehicles



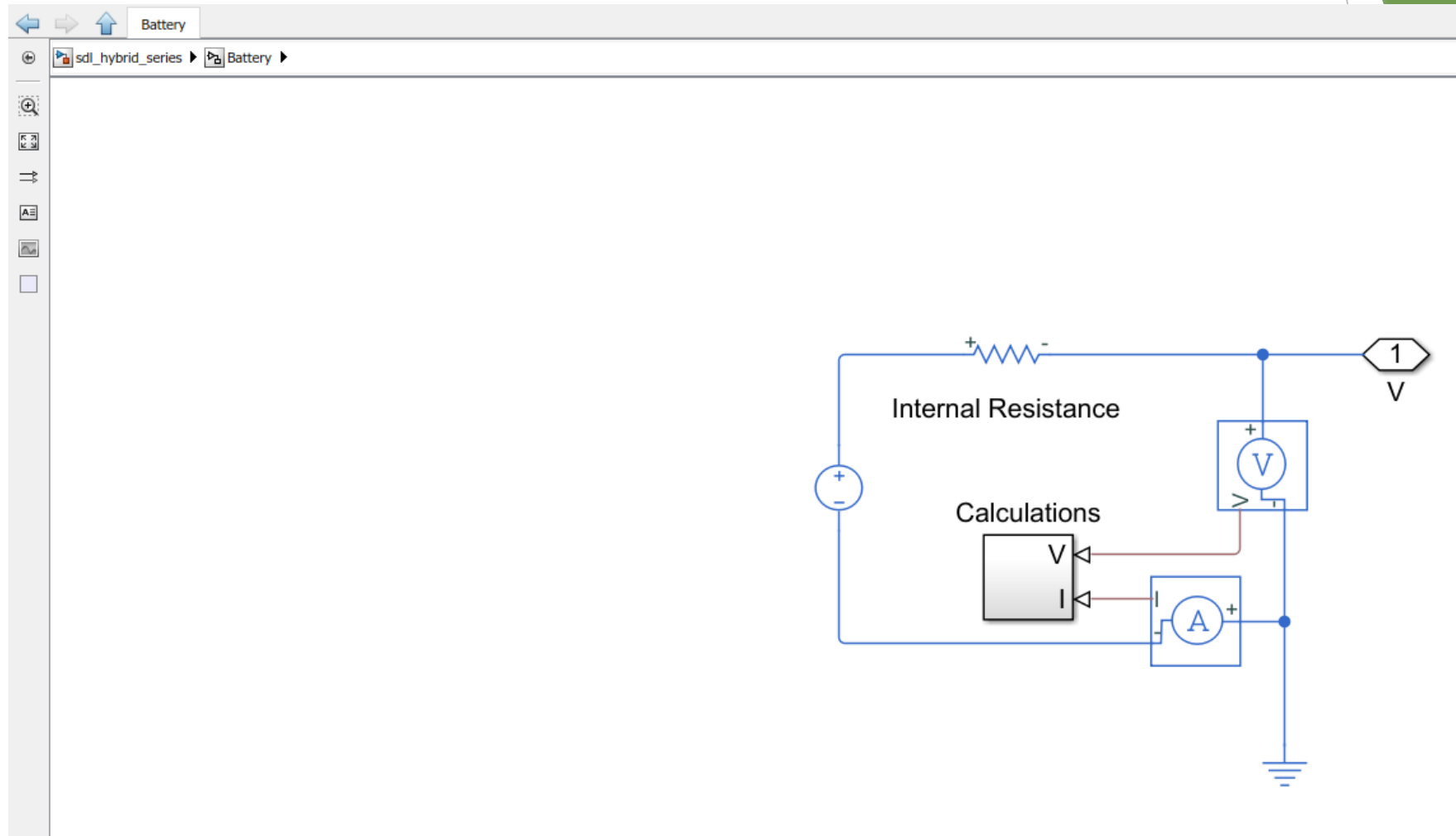
Series Hybrid Transmission - Matlab/Simulink demo

# Simulation of electric vehicles



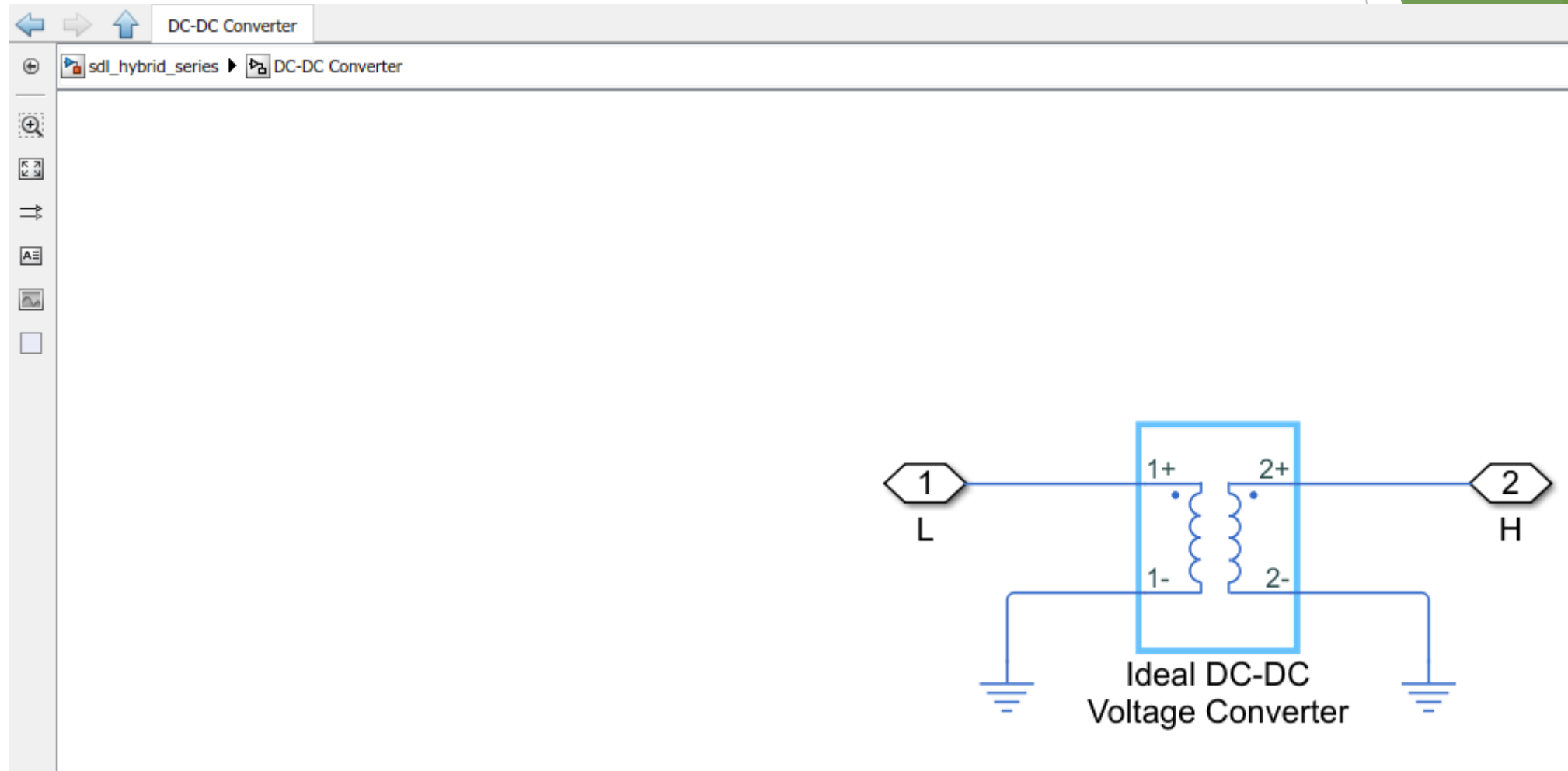
Series Hybrid Transmission - Matlab/Simulink demo (Vehicle Body subsystem)

# Simulation of electric vehicles



Series Hybrid Transmission - Matlab/Simulink demo (Battery subsystem)

# Simulation of electric vehicles

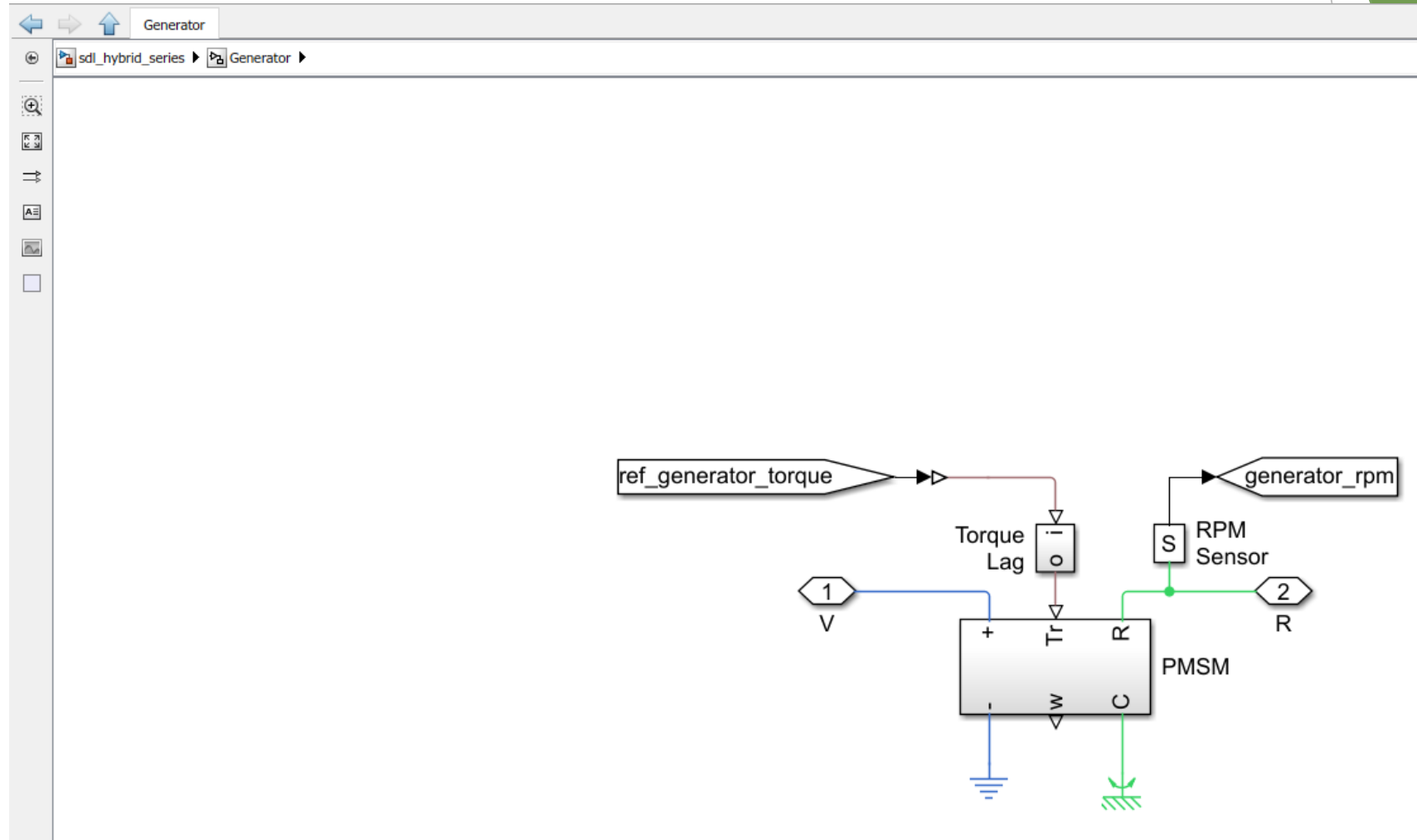


Series Hybrid Transmission - Matlab/Simulink demo (DC-DC Converter subsystem)

The diagram illustrates a control loop for a motor. A reference signal, labeled `ref_motor_rpm`, is fed into a summing junction. The output of the summing junction is the error signal, which is then multiplied by a gain of 2. This gain is represented by a hexagon containing the number 2, with an 'R' below it. The output of the gain block is fed into the 'RPM sensor', which provides the feedback signal `motor_rpm` back to the summing junction.

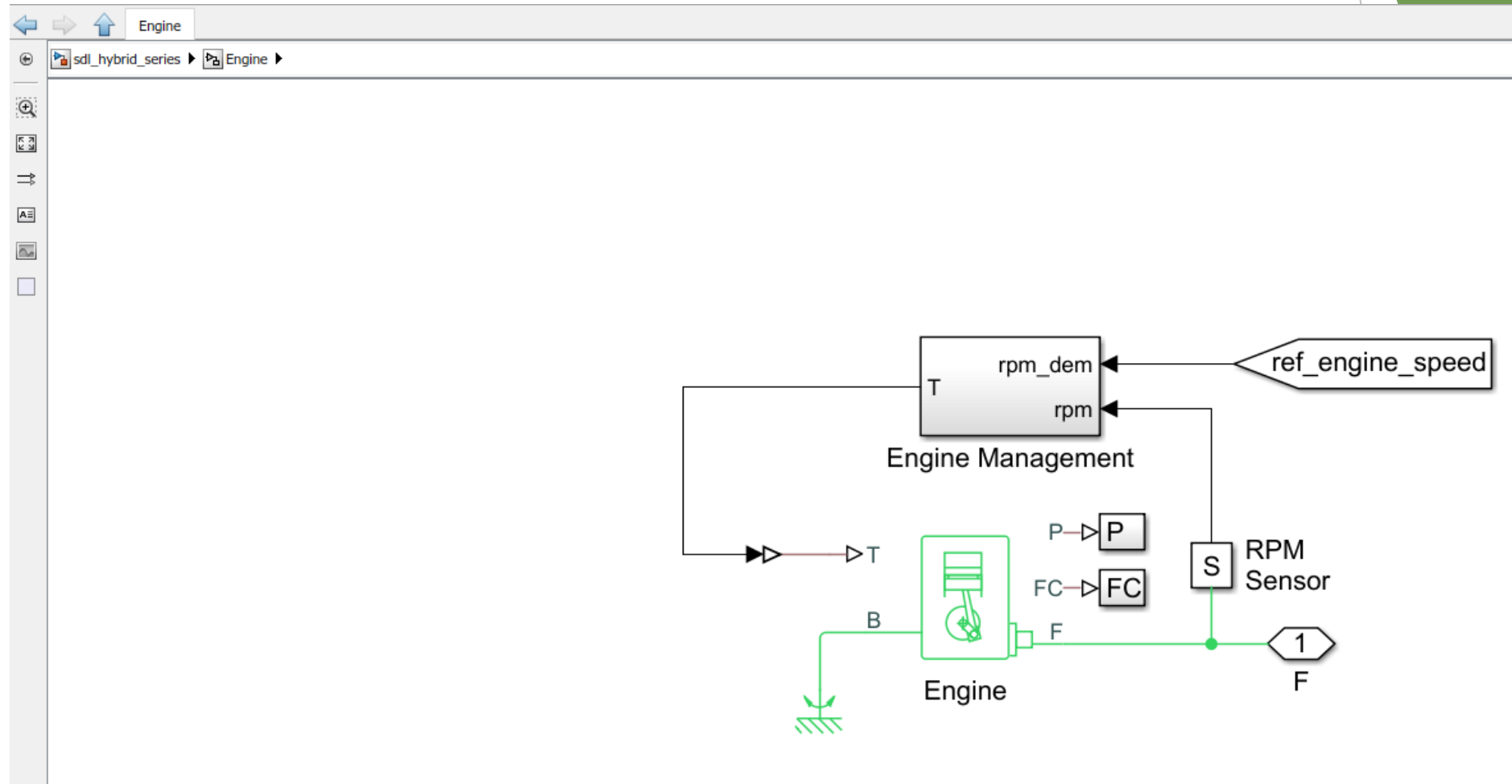


# Simulation of electric vehicles



Series Hybrid Transmission - Matlab/Simulink demo (Generator subsystem)

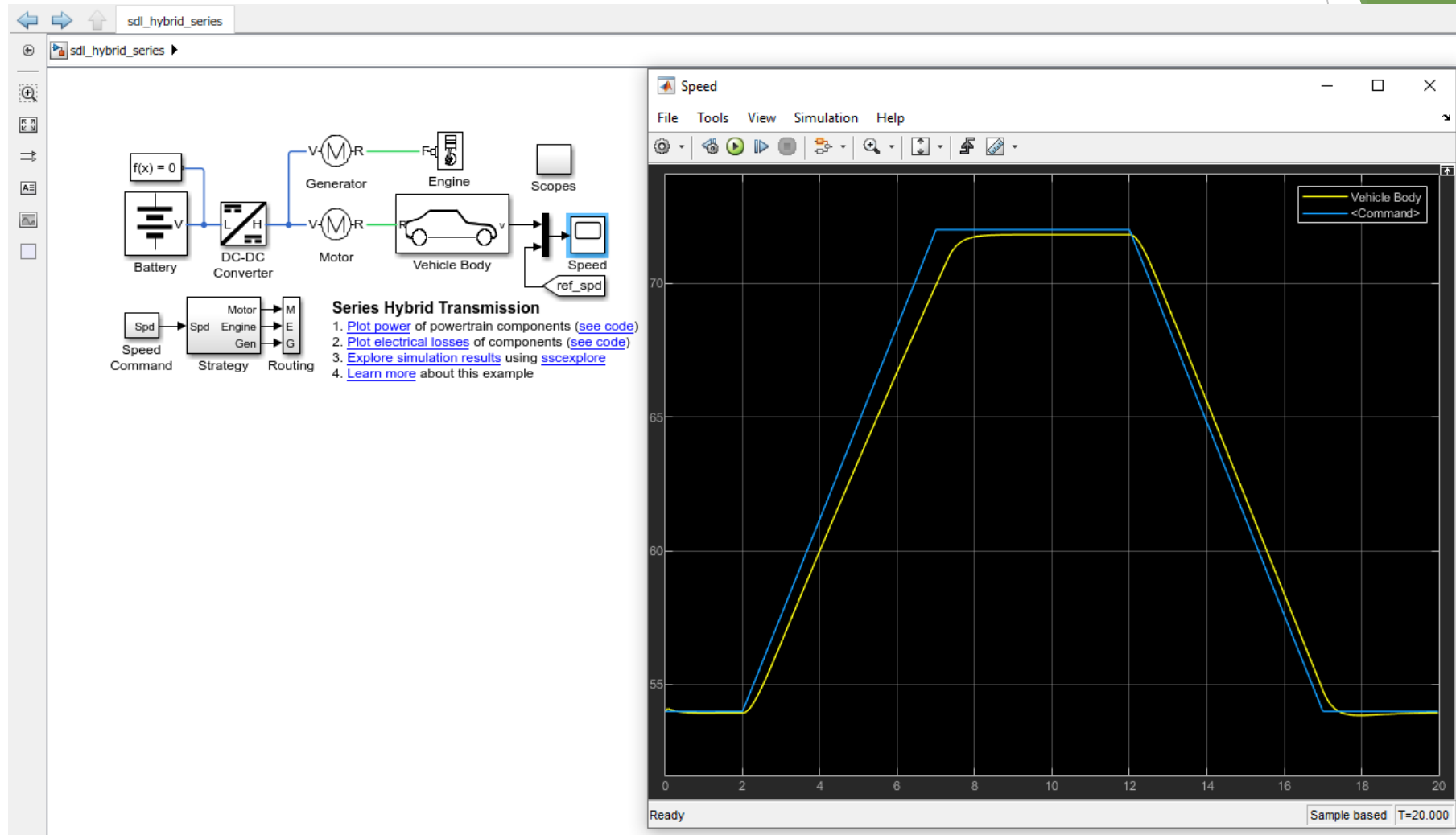
# Simulation of electric vehicles



Series Hybrid Transmission - Matlab/Simulink demo (Engine subsystem)

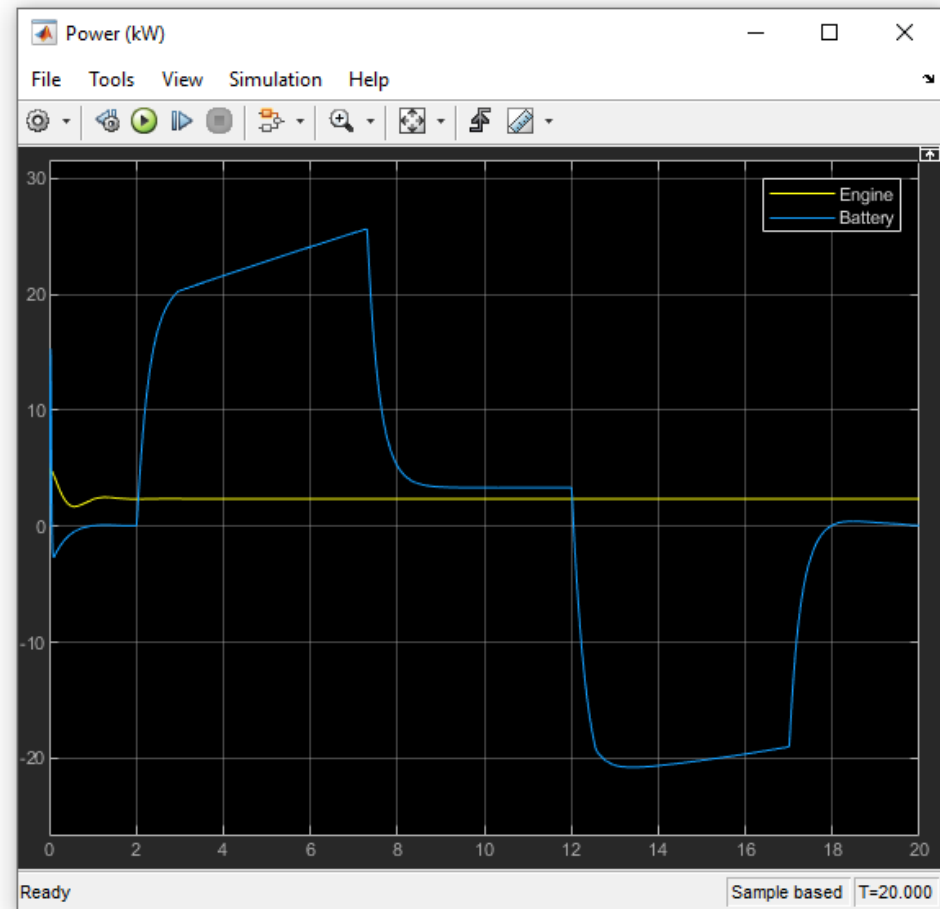
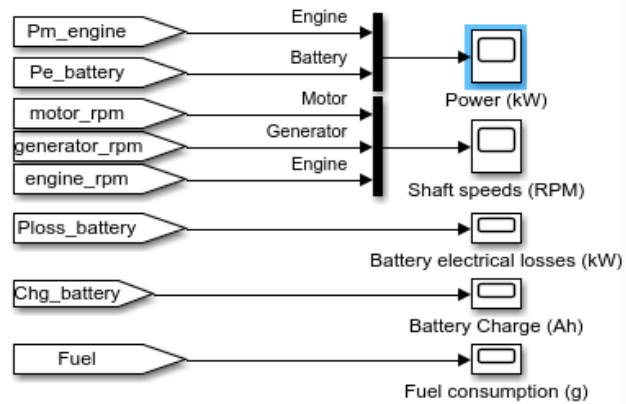


# Simulation of electric vehicles



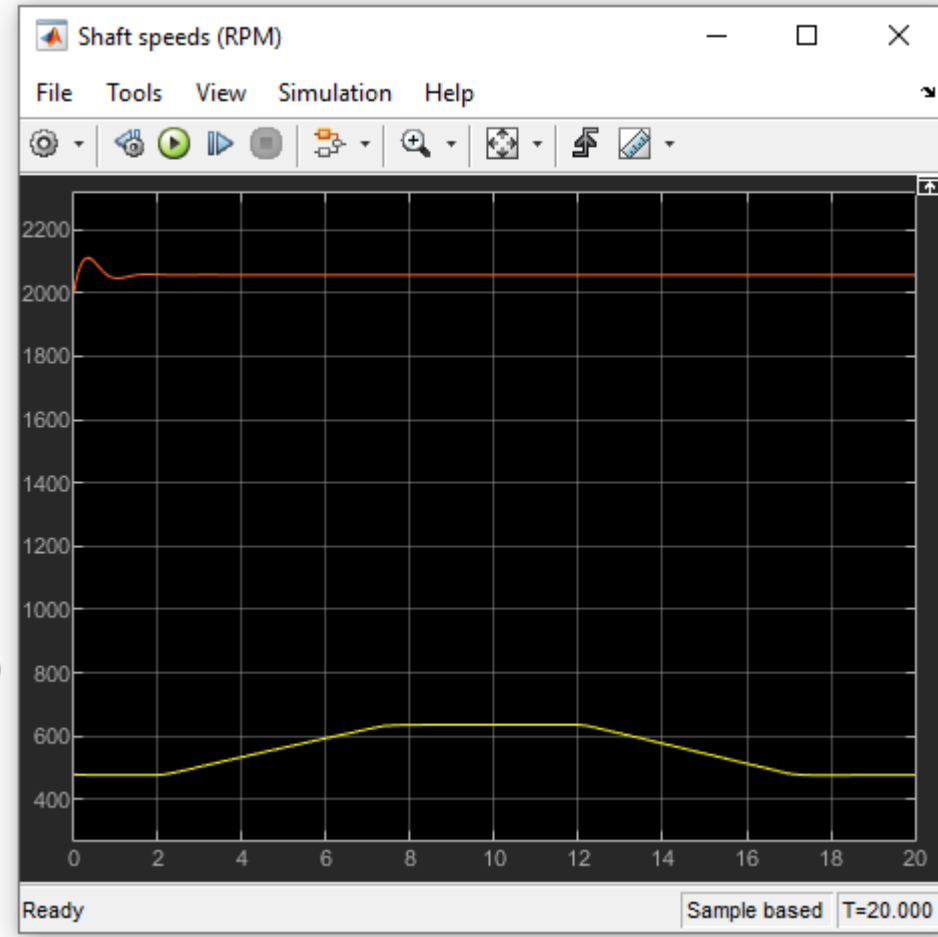
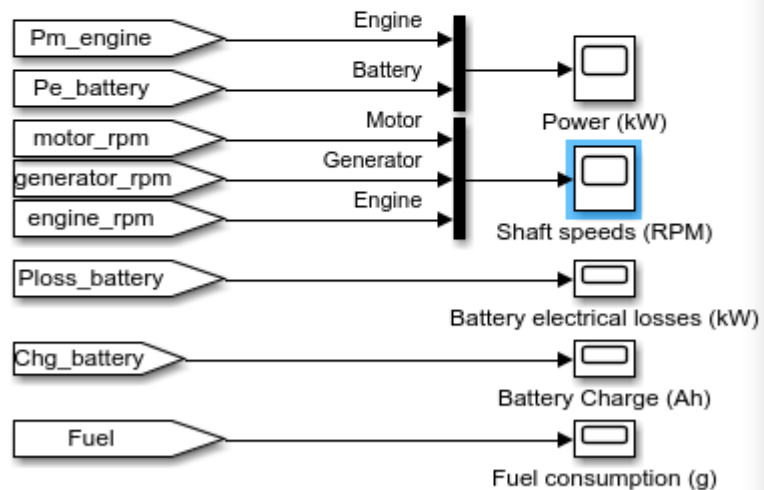
Series Hybrid Transmission - Matlab/Simulink demo (simulated vehicle speed)

# Simulation of electric vehicles



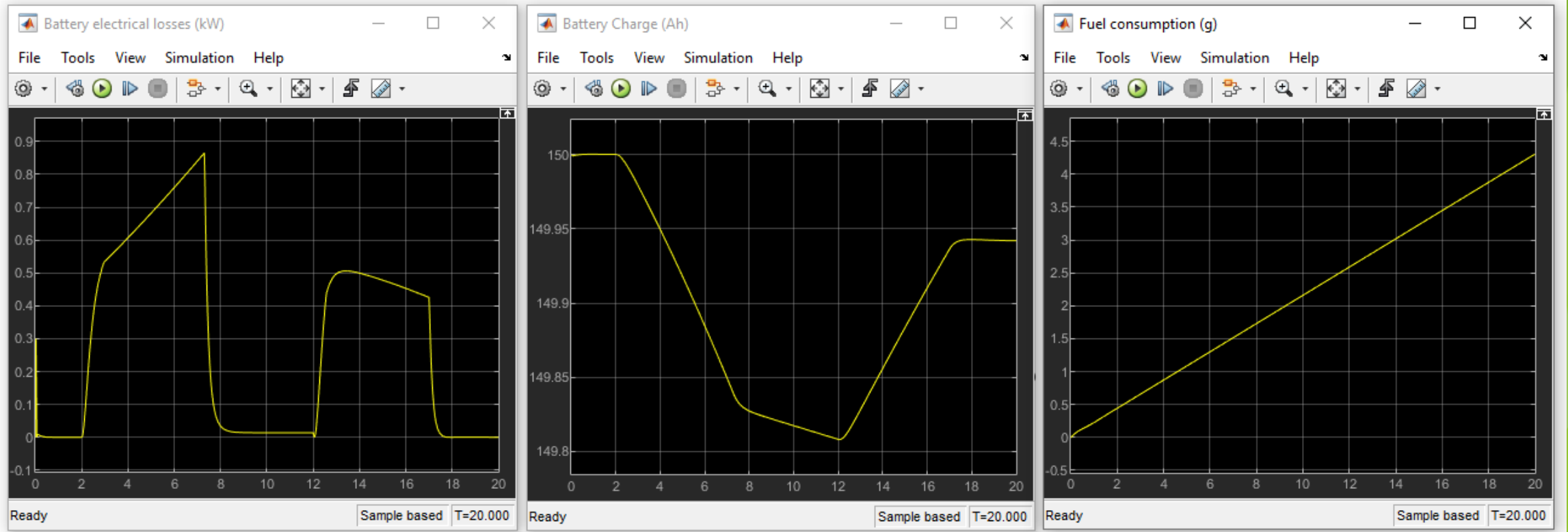
Series Hybrid Transmission - Matlab/Simulink demo (simulated powers)

# Simulation of electric vehicles



Series Hybrid Transmission - Matlab/Simulink demo (simulated shaft speeds)

# Simulation of electric vehicles



Series Hybrid Transmission - Matlab/Simulink demo (simulated battery losses, battery charge and fuel consumption)